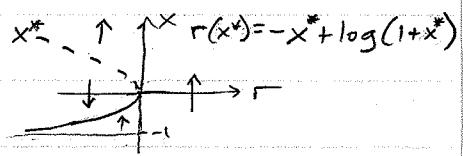
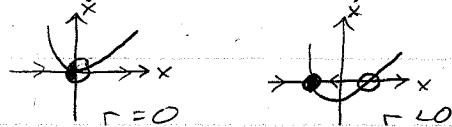


① a) $\dot{x} = r + x - \ln(1+x)$ $r > 0$

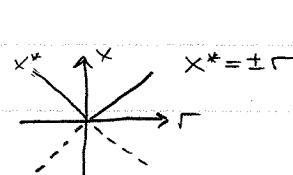
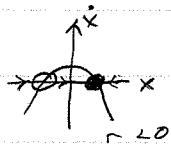
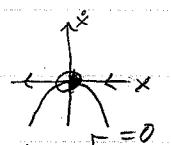
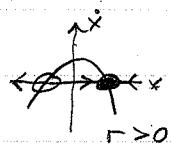
Ian Eisenman

Saddle-node (bifurcation point $r=0, x^*=0$)

Near B.P., $\dot{x} = f(x) \stackrel{\text{Taylor}}{\approx} r + x - \left(x - \frac{x^2}{2}\right) = r + \frac{x^2}{2}$

b)

$$\dot{x} = r^2 - x^2$$



Here there are 2 f.p.s., then 1 at bif pt, then 2 again:

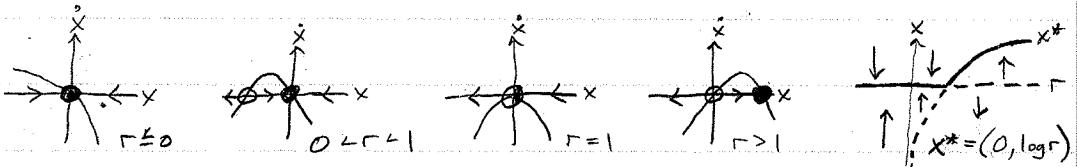
It's a transcritical (bif pt $r=0, x^*=0$).

With the transformation $y = x + r$

$$\dot{x} = \dot{y} = 2y\bar{r} - y^2$$

c)

$$\dot{x} = x(r - e^x)$$

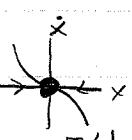
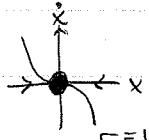
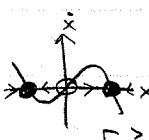
transcritical (B.P.: $r=1, x^*=0$)

Near B.P., $\dot{x} = f(x) \approx x(r-1-x) = (r-1)x - x^2$

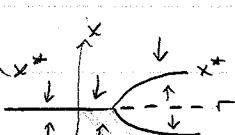
With $R = r-1$, $\dot{x} = Rx - x^2$ (Normal form)

d)

$$\dot{x} = rx - \sinh x$$



$$\begin{aligned} \dot{x} = 0 \text{ when} \\ r(x^*) = \frac{1}{x^*} \sinh x^* \\ \text{or } x^* = 0 \end{aligned}$$

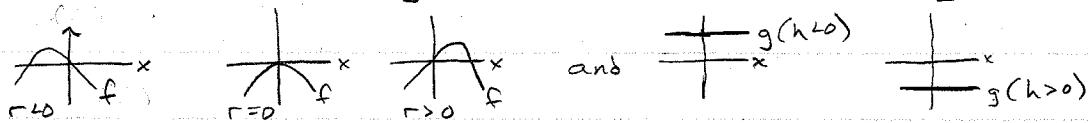
Supercritical pitchfork (B.P.: $r=1, x^*=0$)

Near B.P., $\dot{x} = (r-1)x + x - \left(x + \frac{x^3}{6}\right) = (r-1)x - \frac{x^3}{6}$

With $R = r-1$, $\dot{x} = Rx - \frac{x^3}{6}$

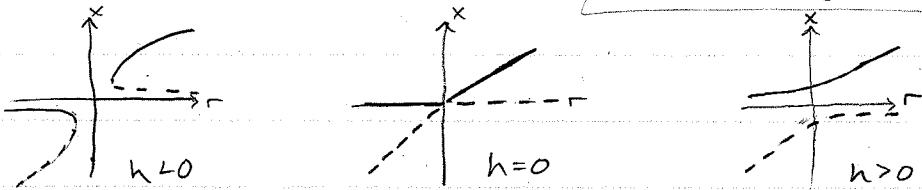
$$(2) \dot{x} = h + rx - x^2$$

i. Let $f(r) = rx - x^2$, $g(h) = -h \Rightarrow$ f.p. where $f = g$

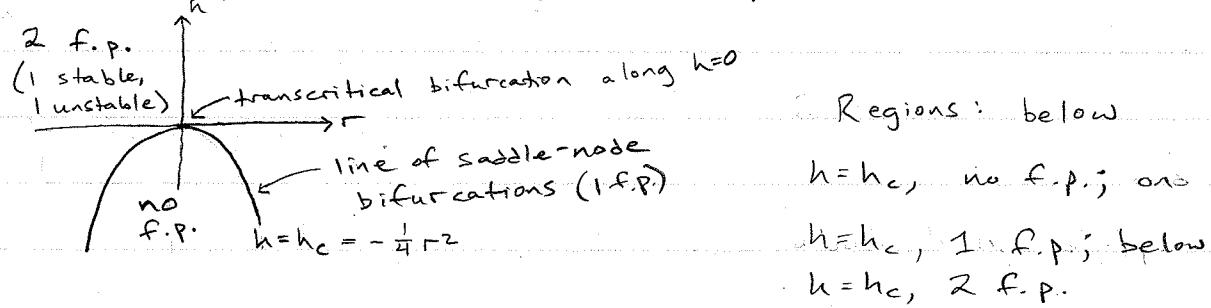


One could sketch the bif diagrams from this alone,

but we'll use $\dot{x} = 0$ at $x^*(r) = \frac{1}{2}(r \pm \sqrt{r^2 - 4h})$



ii. $x^* = \frac{1}{2}(r \pm \sqrt{r^2 - 4h})$, so just one f.p. (bif pt.) when $r^2 - 4h = 0$

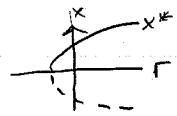


iii. With a perturbation/imperfection, the saddle-node bifurcation looks like this:

It's still a saddle-node, just shifted

(made clear by the transformation $R = r + h$ to $\dot{x} = h + r - x^2$).

The saddle-node, unlike the pitchforks and transcritical, is robust to the addition of an imperfection h (or even hx).



$$(3) \frac{\partial F}{\partial t} + c \frac{\partial F}{\partial x} = 0, \quad c > 0$$

This equation describes advection of F at a speed c .

The solution can be written $F(x, t) = G(x + ct)$. In other words, the curve $F(x, t=0)$ is just shifted along the x -axis at velocity c as time evolves.

Substitute ansatz $F_{mn} = B^{\Delta t} e^{i \omega_m \Delta x}$ into discretized eqn (1):

$$(B^{\Delta t} - B^{-\Delta t}) / 2\Delta t = -c (e^{i \omega_m \Delta x} - e^{-i \omega_m \Delta x}) / 2\Delta x = -\frac{c}{\Delta x} i \sin(\omega_m \Delta x)$$

With $\sigma = \frac{c \Delta t}{\Delta x} \sin(\omega_m \Delta x)$, this is

$$(B^{\Delta t} - B^{-\Delta t}) = -2i\sigma \Rightarrow B^{\Delta t} = -i\sigma \pm \sqrt{1 - \sigma^2}$$

Since $F_{mn} \propto (B^{\Delta t})^n$, the scheme will be unstable

if $|B^{\Delta t}| > 1$ for one of the two roots, which happens

when $|i\sigma| > 1$

So this harmless and totally stable advection equation

can appear unstable when solved with the leapfrog

scheme: in this scenario, a disturbance $F(x, t=0)$

will not only propagate at speed c , but wiggles

will appear and their amplitude will grow exponentially

as an artefact of the numerical scheme.

The conclusion is that if we wish to use the leapfrog scheme (without a Robert filter) to numerically solve a diff. eq. we must choose Δx and Δt carefully so that $|i\sigma| \leq 1$ to avoid artificial instability.